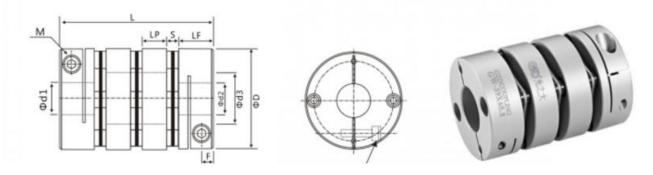
## GW aluminum alloy three diaphragms clamp series Stepping motor servo motor Screw Flexible high torque Flexible Coupling

## **Features**

- 1: With high torque capacity, can accurately control shaft rotation, high precision control can be performed
- 2: The lengthen design more effectively absorb parallel angular misalignments and shaft end-plat
- 3: For servomotor / stepmotor connect
- 4: Zero backlash, Suitable for forward reverse
- 5: Low inertia Suitable for high speed
- 6: Clamping screw fixing method



## Size(unit: mm)

Parameter Modell	frequently used d1,d2 shaft diameter Häufig verwendeter d1, d2 Wellendurchmesser	ФД	L	LF	LP	Φd3	S	F	М	torque (N.m)
GW-19×34	3,4,5,6,6.35,7,8	19	34	9.1	5.2	9	1.8	3.3	M2.5	1
GW-26×44.5	5,6,6.35,7,8,9,9.525,10,11,12,14	26	44.5	11.65	6.5	12.5	2.6	3.9	М3	1.5
GW-32×54	5,6,6.35,7,8,9,9.525,10,11,12,12.7,14,15	32	54	12.25	9.5	15	3.5	3.85	МЗ	1.5
GW-34×58	5,6,6.35,7,8,9,9.525,10,11,12,12.7,14,15,16	34	58	14.25	9.5	16	3.5	4.85	M4	2.5
GW-39×65.5	8,9,9.525,10,11,12,12.7,14,15,16,17,18,19	39	65.5	14.9	11.2	19.3	4.5	5	M4	2.5
GW-44×65.5	8,9,9,525,10,11,12,12.7,14,15,16,17,18,19,20,22,24	44	65.5	14.9	11.2	22.5	4.5	5	M4	2.5
GW-50×73.5	8,9,9.525,10,11,12,12.7,14,15,16,17,18,19,20,22,24,25	50	73.5	17.5	11.0	23	5.5	5.8	M5	7
GW-56×83	10,12,14,15,16,17,18,19,20,22,24,25,28,30,32	56	83	19.75	13.5	32.5	5.5	6.4	M5	7
GW-68×97	12,14,15,16,17,18,19,20,22,24,25,28,30,32,35,38	68	97	23.35	15.7	38.3	6.3	7.7	M6	12
GW-82×128	17,18,19,20,22,24,25,28,30,32,35,38,40,42	82	128	30	22	45.5	8	9.7	M8	20
GW-94×128	19,20,22,24,25,28,30,32,35,38,40,42,43,44,45	94	128	30	22	47.5	8	10	M10	40
GW-104×134	20,22,24,25,28,30,32,35,38,40,42,43,44,45,46,48	104	134	30	22	47.5	10	10	M10	40
GW-126×142	20,22,24,25,28,30,32,35,38,40,42,43,44,45,46,55	126	142	32	20	57.5	12	12	M12	65

notice: torque: tighten the screw torque